

# [High Precision] Motorized X-Axis - Cross Roller



For CAD data, see the MISUMI website.

■ **Features:** X-Axis Stage excellent in lightweight, compactness and accuracy.

■ **X-Axis Motor: C (Standard)**

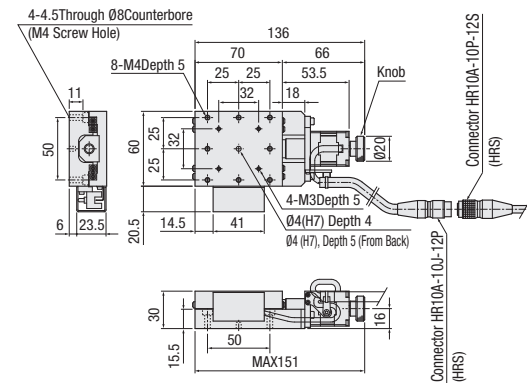
■ **X-Axis Motor: PA (□28 α-Step)**



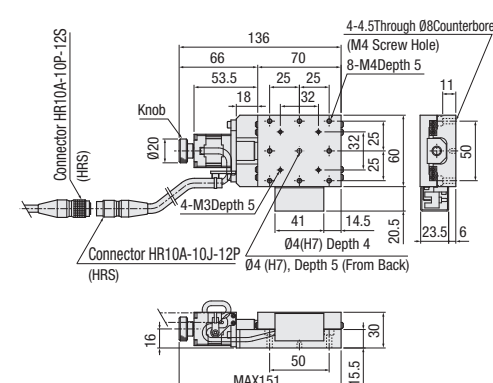
**M** Material: Aluminum Alloy  
**S** Surface Treatment: Black Anodize  
**A** Accessory: SCB4-16 (4 pcs.)

For Controllers, Handset Terminals, see P. 1-1735-93 - P. 1-1735-94

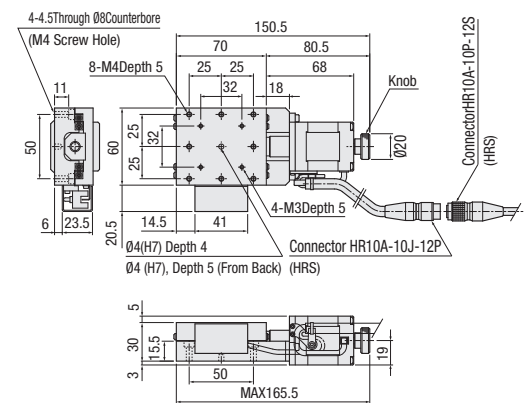
## XMPG730-L-C



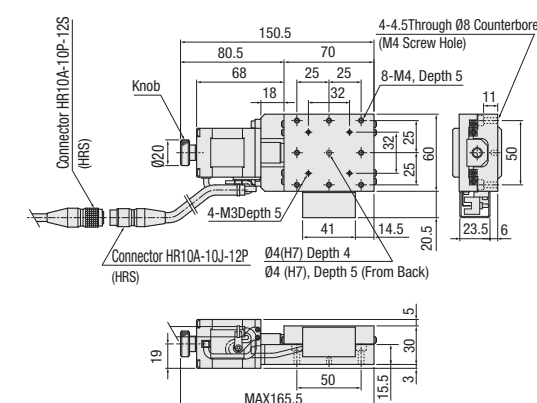
## XMPG730-R-C



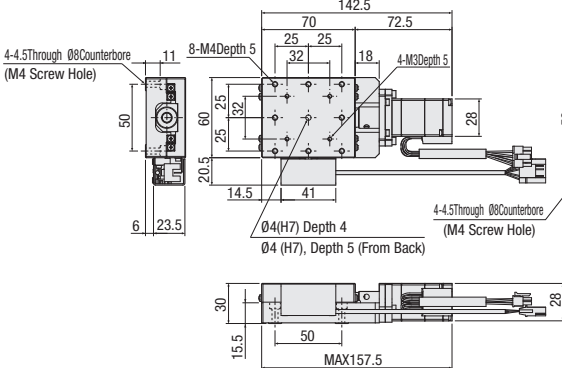
## XMPG730-L-MS



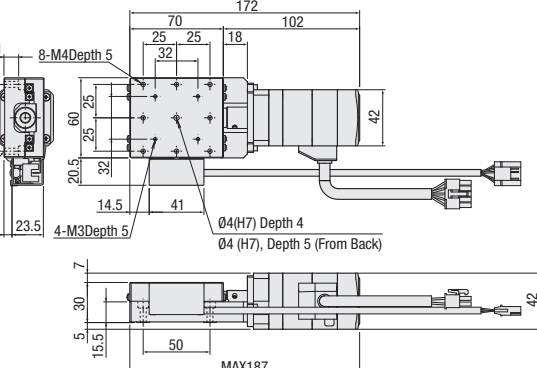
## XMPG730-R-MS



## XMPG730-L-PA



## XMPG730-L-QA



Part Number	Sensor	Motor	Cable	Mechanical Standards			Accuracy Standards *1					
				Stage Surface (mm)	Travel Distance (mm)	Weight (kg)	Unidirectional Positioning Accuracy	Moment Rigidity (N*cm)	Pitching	Yawing	Rolling	Pitching
XMPG730	L (Standard) R (Reversed)	C (Standard)	N (Cable not included (separately sold))	60x70	30	0.6	5μm or less / Full Stroke	0.15	0.08	0.07	25"	20"
		MS (□38 Micro Step)	2A (2m, α-Step) 5A (5m, α-Step) 2R (Robot Cable 2m, α-Step) 5R (Robot Cable 5m, α-Step)									
		PA (□28 α-Step)										
		QA (□42 α-Steps)										

\*1. The above accuracy standards of Unidirectional Positioning Accuracy and Moment Rigidity are for a single axis.



**Ordering Example**  
 Part Number - Sensor - Motor - Cable  
 XMPG730 - L - C - N  
 XMPG730 - R - QA - N

### Motor/Cable Application Table

Motor	Cable
C, MS	N
PA	2A, 5A, 2R, 5R
QA	2A, 5A, 2R, 5R



Configure Online

### Common Specifications

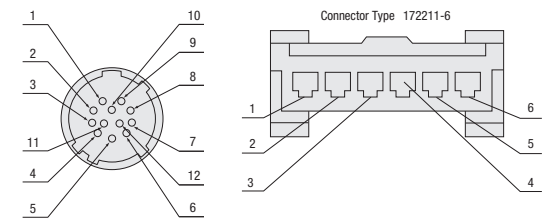
Feed Screw	Ball Screw Ø8, Lead 1
Guide	Cross Roller Guide
Resolution *2	Full 2μm(1μm)*3
	Half 1μm(0.5μm)*3
Max. Speed *4	20mm/sec
Positioning repeatability	Within ±0.3μm
Load Capacity	49N
Lost Motion	1μm or less
Backlash	0.5μm or less
Straightness	3μm or less
Parallelism	30μm or less
Motion Parallelism	10μm or less

\*2. This represents the travel distance of stage per one pulse signal.  
 \*3. The values in ( ) are for Motor Option MS (Micro Step).  
 \*4. This represents the max. speed that can be driven by the recommended controller switched to Full Step mode, with the max. load applied. (The value differs depending on the current driving controller and the current load.)  
 The value differs depending on the motor option.

### Connector Pin Configuration

C: Standard  
 MS: □38 Micro Step

PA: □28 α-Step  
 QA: □42 α-Steps



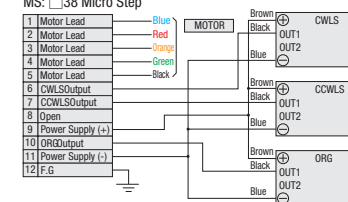
### Electrical Specifications

Part Number	C Standard		MS 38 Micro Step	PA 28 α-Step	QA 42 α-Steps
	Motor	5-Phase Stepping Motor 0.75A/Phase (Oriental Motor Co., Ltd.)			
Motor	Type	PMM338H2-C16-1(□28mm)	C7214-9015-1(□38mm)	ARM24SAK(□28mm)	ARM46AC(□42mm)
	Step Angle	0.72°	0.36°	0.36° (When 1000P/R is set)	
Connector	Driver Part Number	-		ARD-K	ARD-A
	Applicable Receptacle Connector	HR10A-10J-12P (73) (Hirose Electric Co., Ltd.)		172211-6 (Tyco Electronics Japan G.K.)	171822-6 (Tyco Electronics Japan G.K.)
Sensor	Contact Part Number	HR10A-10P-12S (73) (Hirose Electric Co., Ltd.)		170430-1 (Tyco Electronics Japan G.K.)	170205-1 (Tyco Electronics Japan G.K.)
	Applicable Receptacle Contact Part Number	-			
Sensor	Limit Sensor	Provided			
	Slit Home Origin Sensor	Provided			
	Home Sensor	-			
	Power Supply Voltage	Photo Sensor PM-L25 (Panasonic Industrial Devices SUNX Co., Ltd.) DC5-24V or less ±10%			
	Current Consumption	45mA or less (15mA or less per Sensor)			
	Control Output	NPN Open Collector Output DC30V or less, 50mA or less Residual Voltage 2V or less (when load current is 50mA) Residual Voltage 1V or less (when load current is 16mA) Detecting (Dark): Output Transistor OFF (Non-Conducting)			

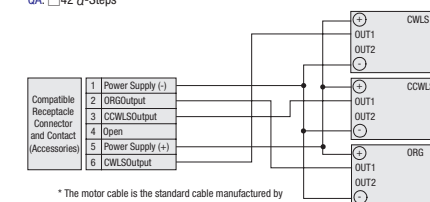
\* Sensors with Part Number PM-□24 are to be discontinued and replaced by next-generation products with Part Number PM-□25 from April 2017.

### Connecting Diagram

C: Standard  
 MS: □38 Micro Step

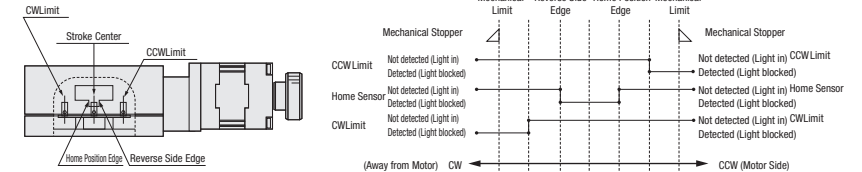


PA: □28 α-Step  
 QA: □42 α-Steps



\* The motor cable is the standard cable manufactured by Oriental Motor Co., Ltd.

### Timing Chart



(Unit: mm)

	Reference Position	Mechanical Limit	CW Limit	Other Signal Edge	Stroke Center	Home Position Edge	CCW Limit	Mechanical Limit
XMPG730	Homing	18.5	17.5	4	2	0	13.5	14.5
	Stroke Center	16.5	15.5	2	0	2	15.5	16.5

\* Homing Routine Above: When DS102/DS112 Series controller is used and when the Homing Routine Type 3 is executed.

\* The coordinates shown are design values. There may be approx. ±0.5mm misalignment on the physical dimensions.

\* For details about Homing, see P. 1-1735-97