

# Single Axis Robot Controllers - Options

# Maintenance Products

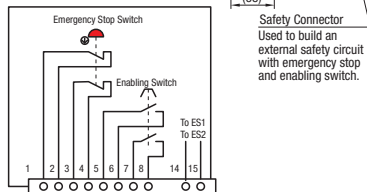
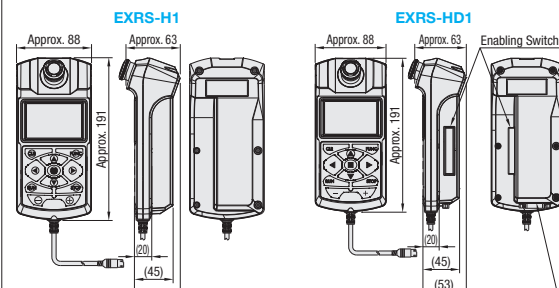
## Options

### Handy Terminal



Part Number	EXRS-H1	EXRS-HD1
Emergency Stop Button	Normally Closed Input (with Lock)	
Deadman's Switch	None	Included (3 Position Enable Switches)
Operating Temp.	0°C~40°C	
Operating Humidity	35%~85%RH (No Condensation)	
Body Mass	Approx. 450g	
Cable Length	3.5m	
Applicable Controller	EXRS-C1/C21/C22	

Part Number	Unit Price	Volume Discount Rate
EXRS-H1	1 pc.	2-3 pcs.
EXRS-HD1		4-5 pcs.



When using a Handy Terminal within the area of motion for the actuator, please use EXRS-HD1 to build safety circuits outside.

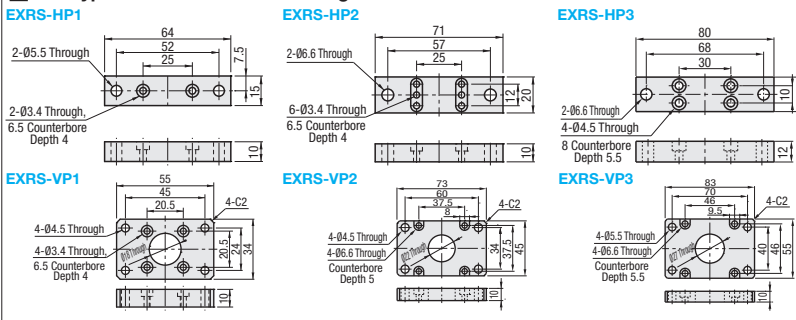
### Support Software (with USB Communication Cable / D-Sub Communication Cable) Communication Specifications: RS232C (EXRS-ST1/ST2)

Part Number	Communication Cable Length	Applicable Controller	Unit Price	Volume Discount Rate
EXRS-ST1	5m	EXRS-C1/C21/C22	1 pc.	2-3 pcs.
EXRS-ST2			4-5 pcs.	

\*The cables are for communications between controller and PC. \*Not applicable to Windows 7 (OS).



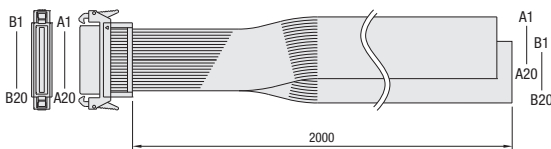
### Rod Type Dedicated Feet and Flanges



### I/O Cable

Part Number	EXRS-CB1
Cable Length	2m
Applicable Controller	EXRS-C1/C21/C22

Part Number	Unit Price	Volume Discount Rate
EXRS-CB1	1 pc.	2-3 pcs.
		4-5 pcs.



Pin No.	Single	Cable Color	Pin No.	Single	Cable Color	Pin No.	Single	Cable Color	Pin No.	Single	Cable Color
A1	+COM	BR	A11	PIN6	BR	B1	POUT0	BR	B11	OUT2	BR
A2	+COM	R	A12	PIN7	R	B2	POUT1	R	B12	OUT3	R
A3	(NC)	OR	A13	JOG+	OR	B3	POUT2	OR	B13	BUSY	OR
A4	(NC)	Y	A14	JOG-	Y	B4	POUT3	Y	B14	END	Y
A5	PIN0	G	A15	MANUAL	G	B5	POUT4	G	B15	/ALM	G
A6	PIN1	BL	A16	ORG	BL	B6	POUT5	BL	B16	SRV-S	BL
A7	PIN2	V	A17	/LOCK	V	B7	POUT6	V	B17	(NC)	V
A8	PIN3	GY	A18	START/TEACH	GY	B8	POUT7	GY	B18	(NC)	GY
A9	PIN4	W	A19	RESET	W	B9	OUT0	W	B19	-COM	W
A10	PIN5	BL	A20	SERVO	BL	B10	OUT1	BL	B20	-COM	BL

\*Connection end to external device is non-terminated.

### Instruction Manual

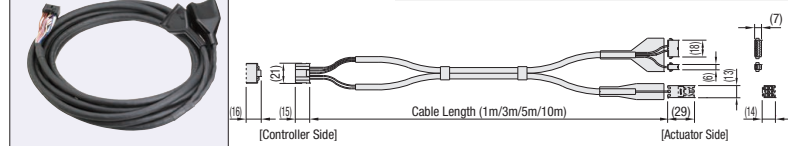
Part Number	Language	Type	Applicable Model	Unit Price	Volume Discount Rate
EXRS-MJ1	Japanese	Instruction Manual for robot main structures is included	RS1/2/3 RSD1/2/3 RSDG1/2/3	1 volume	2-3 volumes
EXRS-MJ2		For Actuator (Clean Version)	RSH1/2/3		
EXRS-MJ3		Instruction Manual for controllers is included	EXRS-C1		
EXRS-MJ4		Instruction Manual for controllers is included	EXRS-C21/C22		
EXRS-KJ1	English	Instruction Manual for robot main structures is included	RS1/2/3 RSD1/2/3 RSDG1/2/3	1 volume	2-3 volumes
EXRS-ME1		For Actuator (Clean Version)	RSH1/2/3		
EXRS-ME2		Instruction Manual for controllers is included	EXRS-C1		
EXRS-ME3		Instruction Manual for controllers is included	EXRS-C21/C22		
EXRS-KE1		Instruction Manual for robot main structures is included	RS1/2/3 RSD1/2/3 RSDG1/2/3	1 volume	2-3 volumes
EXRS-KE2		For Actuator (Clean Version)	RSH1/2/3		

## Maintenance Products

### Power/Signal-Integrated Cables (Flex-Resistant)

(Controller EXRS-C1 ↔ For RS1, 2, 3, 1C, 2C, 3C)  
(Controller EXRS-C1 ↔ For RSD1, 2, 3, RSDG1, 2, 3)

Part Number	Cable Length (m)	Unit Price	Volume Discount Rate
EXRS-CT1	1	1 pc.	2-3 pcs.
	3		4-5 pcs.
	5		
	10		

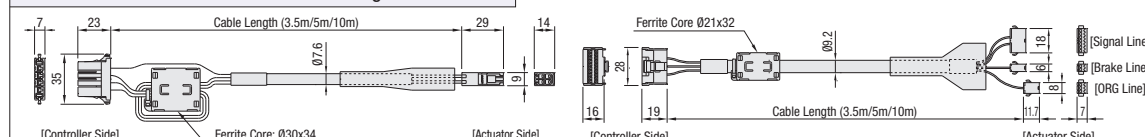


### Power / Signal Cables

(Controller EXRS-C21/C22 ↔ For RSH1, 2, 3, 1C, 2C, 3C)



Part Number	Type	Cable Length	Unit Price	Volume Discount Rate
EXRS-CM1	Power	3.5m:3	1 pc.	2-3 pcs.
		5m:5		4-5 pcs.
EXRS-CR1 (Standard)	Single	3.5m:3		
		5m:5		
EXRS-CR2 (Flexible)	Single	3.5m:3		
		5m:5		
		10m:10		



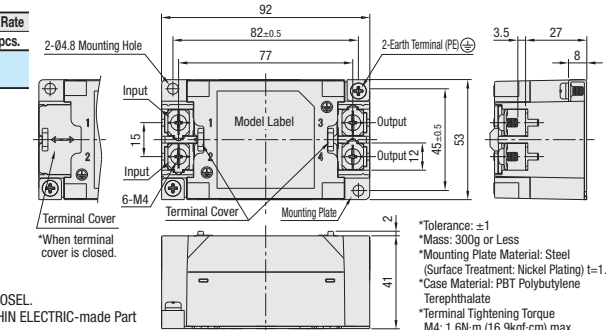
### Noise Filter

Part Number	Rated Voltage	Rated Current	Unit Price	Volume Discount Rate
EXRS-NF1	AC250V/DC250V	10A	1 pc.	2-3 pcs.
				4-5 pcs.

As this product uses push-down type terminal block, it is shipped in the state below.  
\*Terminal cover is stored.  
\*Terminal block screws are kept on the upper side.



\*These listed products are made by COSEL.  
\*Other Recommended Products: SOSHIN ELECTRIC-made Part Number: NF2010A-UP



Ordering Example: Part Number: EXRS-CT1 - Cable Length: 5 Days to Ship [Configure Online](#)

\*Optional items can be purchased more economically as Alterations than as single items.

### Terminology

- Positioning Repeatability**  
Variations in stop positions when positioning moves approached in one direction from one starting location are made.
- Maximum Load Capacity**  
Maximum load that can be placed on the carriage. A sum of the workpiece and the tooling must not exceed this value. Take Allowable Overhang into consideration if the workpiece C.G. is offset from the table center.
- Max. Push Force**  
Maximum thrust force the slider can generate while not moving. Do not perform push and hold actions with shock loading since that may cause failures. Additionally, do not exceed 60% of the Static Load Capacity when the push point is offset from the slider's guide center.
- Rated Force**  
Continuous force that can be generated. For workpiece holding and pushing operations, keep under the Rated Force (approx. 60%). Do not perform shock loading operations even under the Rated Force as that may cause failures. Do not exceed 60% of the Static Load Capacity when the static push point is offset from the slider's guide center.
- Rated Running Life**  
Total running distance where 90% of the Actuators under the same operating condition will reach without failures.
- Allowable Overhang Load**  
Indicates offset distance of tool/workpiece C.G. to the slider's guide center. It depends on the workpiece's load weight and lifetime and running distance of more than 10,000km is achieved when the center of gravity is within allowable overhang. The published values are calculated based on automatically configured acceleration values per given carried mass.
- Allowable Static Moment**  
Moment load value applicable on the slider top surface while the actuator is static. For dynamic applications, overhang value must be determined with running life into consideration.
- Lost Motion**  
A difference in position values when positioning moves are made to a specified coordinate from positive direction to negative direction.
- Rod Non-Rotational Accuracy**  
Rod play in the rotational direction.

### Notes on CE Marking

MISUMI Robot Series provide parts to be incorporated into customers' device and equipment. According to EC Directive, it is declared that these are supplied in an incomplete state. Therefore, no CE marks are attached. Please check for EC Directive compatibility with actuator built-in device or equipment (finished products). For details, please see the Instruction Manual.

### Warranty

- Warranty Terms** Comply with "Warranty Standards" printed on "Mechanical Standard Components for Factory Automation" catalog.
- Warranty Period** One year from shipment date or within the first 2400 hours of operation whichever comes first

### Contact for Inquiry

For inquiries, please contact us at:  
MISUMI Corporation FA Standard Assembly Components Division  
TEL: 03-3647-7300 FAX: 03-3647-7481

### FAQ

- The actuator does not move.  
A1. Invalide activate an actuator using Support Software or Handy Terminal. Invalide activate Option Parameter (80). (Option Valid = I/O Terminal Valid, Option Invalid = I/O Terminal Invalid) Then turn the servo status "ON" and operate the homing.  
After the completion of homing, start the operation by turning on "Operation".
- LED light is on. Is there a controller defect?  
A2. Blue: PWR (OFF: Control Power Shutoff, Blink: Servo OFF, ON: Servo ON), Red: ERR (OFF: Control Power Shutoff / No Error Alarm; Blink: Error Alarm On (External Factor); ON: Error Alarm On (Internal Factor))
- Teaching cannot be conducted by via I/O.  
A3. To conduct teaching via I/O, the status needs to be ON for MANUAL Input and OFF for Interlock Input. Note that it does not function in the state of incompletion of homing.
- Is low-speed operation possible?  
A4. Possible, however, 10 to 20% of max. velocity is the limit depending on the lead.

Ordering Example: Part Number: EXRS-H1

Days to Ship [Configure Online](#)